HIGHER SECANT VARIETIES OF THE MINIMAL ADJOINT ORBIT

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Abstract

The adjoint group of a simple complex Lie algebra \mathfrak{g} has a unique minimal orbit in the projective space $\mathbb{P}\mathfrak{g}$, whose pre-image in \mathfrak{g} we denote by C. We explicitly describe, for every classical \mathfrak{g} and every natural number k, the Zariski closure \overline{kC} of the union kC of all spaces spanned by k points on C. The image of this set in $\mathbb{P}\mathfrak{g}$ is usually called the (k-1)-st secant variety of $\mathbb{P}C$, and its dimension and defect are easily determined from our explicit description. In particular, it follows that the smallest k for which \overline{kC} is equal to \mathfrak{g} , is n for \mathfrak{sl}_n , 2n for \mathfrak{sp}_{2n} , 4 for \mathfrak{or}_7 , and $\lfloor \frac{n}{2} \rfloor$ for \mathfrak{or}_n , $n \geq 8$; we find that the upper bound on this k provided by a theorem of Zak on secants of general varieties, is off by a factor of 2 in the cases of \mathfrak{sl}_n and \mathfrak{or}_n , but sharp for \mathfrak{sp}_{2n} .

The orthogonal Lie algebras turn out to be the most difficult, by far: while all sets kC are closed in the other two cases, this is not true for 2C in \mathfrak{o}_n , and we discuss the problems arising in describing the sets kC for $k \geq 3$. In particular, we do not know the smallest k for which kC is equal to \mathfrak{o}_n , though we do prove that it is at most $\lfloor \frac{n}{2} \rfloor + 3$.

1. Introduction and results

The projective space $\mathbb{P}\mathfrak{g}$, where \mathfrak{g} is a semisimple Lie algebra over an algebraically closed field K of characteristic zero, has a unique minimal orbit under the action of the adjoint group of \mathfrak{g} ; let C denote the pre-image of this orbit in \mathfrak{g} . Here 'minimal' refers to the inclusion order among orbit closures, so the minimality of $\mathbb{P}C$ means that it is contained in the closure of any other orbit. The set C, itself a nilpotent orbit, plays an important role in several branches of Lie theory: First, C consists of all long root vectors relative to appropriate Cartan subalgebras (or of all highest root vectors relative to Borel subalgebras) and is therefore of interest in representation theory. Alternatively, C may be described as the set of all nonzero $X \in \mathfrak{g}$ for which $[X,[X,\mathfrak{g}]] \subseteq KX$ [13], and these extremal elements pop up in the classification of Lie algebras in positive characteristic [6, 19] (for a possible connection between our results and those of [6], see the conclusion of this paper). We, now, are to discuss properties of C that are interesting from a geometric point of view, namely: what do the higher secant varieties of $\mathbb{P}C$ in $\mathbb{P}\mathfrak{g}$ look like, and what are the corresponding defects of $\mathbb{P}C$? This work is part of a larger project, which asks for the secant varieties of the minimal orbit in any irreducible representation of any reductive algebraic group.

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Recall that the (k-1)-st secant variety of $\mathbb{P}C$ in the projective space $\mathbb{P}\mathfrak{g}$ is the Zariski closure of the union of all projective subspaces of $\mathbb{P}\mathfrak{g}$ spanned by k points on $\mathbb{P}C$. As C is a cone, this secant variety is in fact equal to $\mathbb{P}(\overline{kC}\setminus\{0\}) = \mathbb{P}(kC\setminus\{0\})$ where kC is the set defined by

$$kC := \{J_1 + \ldots + J_k \mid J_i \in C \text{ for all } i\}.$$

The expected dimension of kC is min $\{k \dim C, \dim \mathfrak{g}\}$, and this expected dimension minus the actual dimension of kC is usually called the (k-1)-defect of C (or of $\mathbb{P}C$).

We are to present explicit descriptions of the sets \overline{kC} in the case where \mathfrak{g} is classical, which extend the results on the first secant variety of $\mathbb{P}C$ by Kaji et al [13, 14]. It should be mentioned that their method applies to the exceptional simple Lie algebras, as well, while it is not obvious how to uniformise our caseby-case approach so as to incorporate those in our treatment. Closely related to the matter of this paper is also [4], which treats the higher secant varieties of the variety of indecomposable tensors in a tensor product.

The research on higher secant varieties of general varieties finds its origin in the works of Palatini and Terracini [18, 20], and an important part of this research concerns (bounds on) the dimensions of secant varieties, as well as the construction of concrete varieties attaining these dimensions [1, 2, 3, 8, 10, 17, 21]. The monograph [21] by Zak contains the following result that we compared to our concrete situation: suppose that the first defect δ of an irreducible smooth n-dimensional projective algebraic variety X, lying in and spanning \mathbb{P}^N , is non-zero. Then the smallest k for which the k-th secant variety of X is equal to \mathbb{P}^N , is at most $\lfloor \frac{n}{\delta} \rfloor$. Though derived for application to varieties that—unlike the minimal orbit $\mathbb{P}C$ have low codimension in the ambient projective space, this bound turns out to be quite good for the minimal orbit: it is roughly twice the actual value for \mathfrak{sl}_n and \mathfrak{o}_n , and it is sharp for \mathfrak{sp}_{2n} .

Turning our attention to a classical Lie algebra \mathfrak{g} , we define the rank of an element $A \in \mathfrak{g}$, denoted $\operatorname{rk}(A)$, to be its rank as a linear map in the standard \mathfrak{g} -module V. In the cases of \mathfrak{sl}_n and \mathfrak{sp}_{2n} the minimal orbit C consists of all elements of rank 1, and the following theorem, the subject of Section 2, identifies the secant varieties of study as certain determinantal varieties.

Theorem 1.1. If
$$\mathfrak{g} = \mathfrak{sl}_n$$
 $(n \geq 2)$ or $\mathfrak{g} = \mathfrak{sp}_{2n}$ $(n \geq 2)$, then we have $kC = \overline{kC} = \{A \in \mathfrak{g} \mid \operatorname{rk}(A) \leq k\}$ for all $k, 2 \leq k \leq n$.

This is not new for \mathfrak{sl}_n : [15] contains a proof using the Jordan normal form, while our proof was inspired by [12, §56, Exercise 6].

(1) For $\mathfrak{g} = \mathfrak{sl}_n$ and $1 \leq k \leq n$ the dimension of kC is 2kn - 1Corollary 1.2.

$$k^{2} - 1, \text{ so that the } (k - 1)\text{-defect of } C \text{ is } \min\{(k - 1)^{2}, (n - k)^{2}\}.$$

$$(2) \text{ For } \mathfrak{g} = \mathfrak{sp}_{2n} \text{ and } 1 \leq k \leq 2n \text{ the dimension of } kC \text{ is } \binom{2n+1}{2} - \binom{2n+1-k}{2},$$
so that the $(k - 1)\text{-defect of } C \text{ is } \min\{\binom{k}{2}, \binom{2n+1-k}{2}\}.$

The result for \mathfrak{o}_n is radically different; we assume $n \geq 7$ here, as the other (simple) cases are dealt with by the preceding theorem. Now we have

$$C = \{J \in \mathfrak{o}_n \mid \operatorname{rk}(J) = 2 \text{ and } J^2 = 0\}$$
 (see Subsection 3.1),

and one might hope that kC is simply the set of all elements of rank at most 2k—but this is not true! To describe the first and the second secant variety, denote by $S_2 \subseteq$

 \mathfrak{o}_n the set of all semisimple elements of rank 4 whose non-zero eigenvalues (on V) are a, a, -a, -a for some $a \in K^*$. Similarly, let $S_3 \subset \mathfrak{o}_n$ be the set of all semisimple elements of \mathfrak{o}_n of rank 6 with 6 distinct non-zero eigenvalues $a, b, c, -a, -b, -c \in K$ satisfying a + b + c = 0. We then have the following theorem (Section 3).

Theorem 1.3. For $\mathfrak{g} = \mathfrak{o}_n$ $(n \geq 7)$ the sets $\overline{2C}$ and $\overline{3C}$ are equal to $\overline{S_2}$ and $\overline{S_3}$, respectively, while for $k \geq 4$ we have $\overline{kC} = \{A \in \mathfrak{o}_n \mid \operatorname{rk}(A) \leq 2k\}$.

Corollary 1.4. For $\mathfrak{g} = \mathfrak{o}_n$ $(n \geq 7)$ the dimensions of C, 2C, 3C, and kC $(4 \leq k \leq \lfloor \frac{n}{2} \rfloor)$ are 2n-6, 4n-13, 6n-22, and $\binom{n}{2} - \binom{n-2k}{2}$, respectively (the dimension of 4C in \mathfrak{o}_7 is $\binom{7}{2}$). Hence, the (k-1)-defect of C is equal to 1 for k=2, equal to 4 for k=3, and equal to $\min\{k(2k-5), \binom{n-2k}{2}\}$ if $k\geq 4$ (and zero for (k,n)=(4,7)).

Note that Theorem 1.3 only mentions the closures \overline{kC} , not the sets kC themselves. This is because we do not know their exact structure; we now list what we do know. First, the set 2C is already not closed; indeed, Kaji et al determined the nilpotent orbits lying in its closure [14], and it turns out that $\overline{2C} \setminus 2C$ consists of a single such orbit. To formulate our proposition to that effect, recall that nilpotent orbits of O_n on \mathfrak{o}_n correspond, through the Jordan normal form, to partitions of n whose even entries have even multiplicities. If $\mathbf{d} = (d_1, \ldots, d_m)$, $d_1 \geq d_2 \geq \ldots \geq d_m$ is such a partition, then we denote by $\mathcal{O}[\mathbf{d}] = \mathcal{O}[d_1, \ldots, d_m]$ the corresponding nilpotent orbit. For example, in this notation we have $C = \mathcal{O}[2, 2, 1^{n-4}]$.

Proposition 1.5. The set 2C is equal to $\overline{2C} \setminus \mathcal{O}[3,2,2,1^{n-7}]$.

The fact that $\overline{2C} \setminus 2C$ is a nilpotent orbit suggests to determine, for a general nilpotent orbit \mathcal{O} , the smallest k for which \mathcal{O} is contained in kC. Our partial result in this direction uses the notation $l(\mathbf{d}) := |\{i \mid d_i \text{ is odd, } d_i > 1\}|$. Furthermore, by the rank of an orbit \mathcal{O} we shall mean the rank of an element of that orbit.

Theorem 1.6. Let \mathbf{d} be a partition of n as above, and let 2k be the rank of $\mathcal{O}[\mathbf{d}]$. Then $\mathcal{O}[\mathbf{d}]$ is contained in (k+1)C. If moreover $l(\mathbf{d})$ is even, or if $l(\mathbf{d})$ is odd and $d_1 > 5$, then $\mathcal{O}(\mathbf{d})$ is already contained in kC.

The upper bound k+1 (notation as in the preceding theorem) is sharp for $\mathbf{d}=[3,2,2,1^{n-7}],[3,1^{n-3}],$ and $[5,1^{n-5}].$ Hence, the nilpotent orbits of smallest rank for which we do not know the smallest kC containing them, are $\mathcal{O}[3,3,3,1^{n-9}]$ and $\mathcal{O}[5,2,2,1^{n-9}],$ both of rank 6. In conclusion, it seems hard to write a general element of \mathfrak{o}_n as a sum of as few as possible elements of C. The rank reduction argument used to prove Theorem 1.3, however, does give an upper bound to the maximum number of terms needed.

Theorem 1.7. Every element of \mathfrak{o}_n having rank at most 2k lies in (k+3)C. In particular, $(\lfloor \frac{n}{2} \rfloor + 3)C = \mathfrak{o}_n$.

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2. Appetisers: \mathfrak{sl}_n and \mathfrak{sp}_n

For all classical simple Lie algebras \mathfrak{g} the minimal orbit C consists of matrices of some low rank r (r=1 for \mathfrak{sl}_n and \mathfrak{sp}_{2n} , and r=2 for \mathfrak{o}_n ; see below). As a result, an element of kC has rank at most kr. Now if A lies in kC, then by definition there exists a $J \in C$ such that $A - J \in (k-1)C$, hence if A has the

maximal possible rank kr, then its rank must decrease by r upon subtracting J: $\mathrm{rk}(A-J)=\mathrm{rk}(A)-r=(k-1)r$. It seems therefore reasonable, given an element $A\in\mathfrak{g}$ that we want to write as a sum of points on C, to look for $J\in C$ such that $\mathrm{rk}(A)-\mathrm{rk}(J)<\mathrm{rk}(A)$. The easy lemma below turns out to be an effective tool in the quest for such J.

Here, and in the rest of this paper, V stands for the standard module of the classical Lie algebra under consideration, V^* denotes the linear dual of V, and $\langle .,. \rangle$ is the natural pairing $V \times V^* \to K$. We identify $\mathfrak{gl}(V)$ with $V \otimes V^*$, and recall that under this identification the rank one elements of $\mathfrak{gl}(V)$ correspond to the tensors $y \otimes \eta$ with non-zero $y \in V$ and $\eta \in V^*$. Furthermore, for $A \in \mathfrak{gl}(V)$ we define the dual map $A^* \in \mathfrak{gl}(V^*)$ by $\langle x, A^*\xi \rangle = \langle Ax, \xi \rangle$.

Lemma 2.1. For $A \in \mathfrak{gl}(V)$ and non-zero elements $y \in V, \eta \in V^*$ we have

- (1) $\operatorname{rk}(A y \otimes \eta) < \operatorname{rk}(A)$ if and only if $y \in \operatorname{im} A$, $\operatorname{ker} \eta \supseteq \operatorname{ker} A$, and $\langle x, \eta \rangle = 1$ for some (and hence for any) $x \in A^{-1}y$; and
- (2) $y \otimes \eta$ lies in $\mathfrak{sl}(V)$ if and only if $\langle y, \eta \rangle = 0$.

Remark 2.2. The conditions in the first statement are self-dual in y and η , and can be rephrased more compactly as $\langle A^{-1}y, \eta \rangle = \{1\}$ or as $\langle y, (A^*)^{-1}\eta \rangle = \{1\}$.

Proof. The second statement is obvious. As for the first statement: if y and η satisfy the stated conditions, then $\ker(A-J) = \ker A \oplus Kx$, so that $\operatorname{rk}(A-J) < \operatorname{rk}(A)$ as claimed. Conversely, suppose that $\operatorname{rk}(A-J) < \operatorname{rk}(A)$, and let x' be an element of $\ker(A-J) \setminus \ker A$. Then $(A-J)x' = Ax' - \langle x', \eta \rangle y = 0$ while $Ax' \neq 0$. We conclude that $c := \langle x', \eta \rangle$ is non-zero, so that we may set x := x'/c. Now $\langle x, \eta \rangle = 1$ and Ax = y and, by a dual argument, η lies in $\operatorname{im} A^*$, which is equivalent to $\ker \eta \supseteq \ker A$.

Now first consider the Lie algebra \mathfrak{sl}_n with standard module $V = K^n$. The highest root vector with respect to the usual Cartan and Borel subalgebras of \mathfrak{sl}_n is the matrix with zeroes everywhere and a 1 in the upper right corner, hence of rank one. It is easy to see that the rank one elements of \mathfrak{sl}_n form one orbit under the adjoint group PSL_n : the minimal orbit C. Now we are ready to prove Theorem 1.1 in the case where $\mathfrak{g} = \mathfrak{sl}_n$.

Proof of Theorem 1.1 for $\mathfrak{g}=\mathfrak{sl}_n$. Let $A\in\mathfrak{sl}_n$ be non-zero; we show that there exists a $J\in C$ for which $\mathrm{rk}(A-J)=\mathrm{rk}(A)-1$. Indeed, A induces a linear map \bar{A} on the non-zero space $V/\ker A$, and we have $\mathrm{tr}\,\bar{A}=0$. As K has characteristic 0, the map \bar{A} , having trace zero, cannot be a non-zero scalar, so that there exists an $x\in V$ for which $x+\ker A$ is not a scalar multiple of $\bar{A}(x+\ker A)$. This means that x does not lie in $KAx+\ker A$, hence there exists a linear function $\eta\in V^*$ that vanishes on $KAx+\ker A$ but has the value 1 on x. Now $J:=Ax\otimes \eta$ lies in \mathfrak{sl}_n and has $\mathrm{rk}(A-J)=\mathrm{rk}(A)-1$ by Lemma 2.1.

By induction, this proves that every element of \mathfrak{sl}_n of rank k lies in kC, for $k=1,\ldots,n$. The inclusions $kC\subseteq (k+1)C$ and $0\in 2C$, following from the fact that C is a cone, conclude the proof that for $k\geq 2$ every element of rank at most k lies in kC. Conversely, it was observed at the beginning of this section that kC does not contain elements of rank higher than k.

We proceed to prove Theorem 1.1 for the symplectic Lie algebra \mathfrak{sp}_{2n} . Let $V=K^{2n}$ be the standard \mathfrak{sp}_{2n} -module, and denote by (.,.) the non-degenerate

skew bilinear form on V defining \mathfrak{sp}_{2n} . Define the linear maps $\phi: V \to V^*$ and, for $A \in \mathfrak{gl}(V)$, $A^T: V \to V$ by $\langle x, \phi y \rangle = (x, y)$ and $(x, A^T y) = (Ax, y)$ for $x, y \in V$ and $\eta \in V^*$. We first describe the minimal Sp_{2n} -orbit C in \mathfrak{sp}_{2n} in a convenient way.

Lemma 2.3.
$$C = \{x \otimes \phi x \mid x \in V \setminus \{0\}\} = \{J \in \mathfrak{sp}_{2n} \mid \operatorname{rk} J = 1\}.$$

Proof. First, the highest root vector in \mathfrak{sp}_{2n} (with respect to some choice of Cartan and Borel subalgebras) is easily seen to have rank one. Now a rank one element $J = y \otimes \eta$ of \mathfrak{gl}_{2n} lies in \mathfrak{sp}_{2n} if and only if (Jx, z) = -(x, Jz) or, filling in the expression for J, if

$$\langle x, \eta \rangle (y, z) = -(x, y) \langle z, \eta \rangle$$

for all $x, z \in V$. By skewness of the form, this is clearly the case if $\eta = \phi(y)$. Conversely, for $z \in V$ fixed such that $(y, z) \neq 0$, the equation above shows that $\eta = c\phi(y)$ for some $c \neq 0$; hence if d is a square root of c, then $J = y \otimes \eta = dy \otimes \phi(dy)$. This shows that the second set of the lemma is equal to the third, and that they contain C. Finally, the transitivity of Sp_{2n} on $V \setminus \{0\}$ implies the transitivity of Sp_{2n} on the second set of the lemma, and this concludes the proof.

Proof of Theorem 1.1 for \mathfrak{sp}_{2n} . Let $A \in \mathfrak{sp}_{2n}$ be non-zero. We show that there exists an $x \in V$ such that $A - (Ax \otimes \phi(Ax))$ has rank $\mathrm{rk}(A) - 1$. By Lemma 2.1 this is the case if and only if $\ker \phi(Ax) \supseteq \ker A$ and $\langle x, \phi(Ax) \rangle = 1$. The first condition holds for all $x \in V$, as Az = 0 implies

$$\langle z, \phi(Ax) \rangle = (z, Ax) = -(Az, x) = 0$$

by virtue of $A^T = -A$. Hence, we are left to show that there exists an $x \in V$ for which $\langle x, \phi(Ax) \rangle = (x, Ax) \neq 0$; rescaling x will then make this scalar 1. Suppose, on the contrary, that (x, Ax) = 0 for all x. Then we have for all $x, y \in V$:

$$0 = (x + y, A(x + y)) = (x, Ax) + (y, Ay) + (x, Ay) + (y, Ax) = 2(x, Ay),$$

so that A = 0, which contradicts our assumption that rk(A) be greater than 1.

By induction, this shows that for $k=1,\ldots,2n$ every element of \mathfrak{sp}_{2n} of rank k lies in kC. As in the case of \mathfrak{sl}_n , the inclusions $kC\subseteq (k+1)C$ and $0\in 2C$, together with the fact that kC cannot contain elements of rank higher than k, conclude the proof.

3. The main course: \mathfrak{o}_n

Now we come to the more intricate part of this paper: the secant varieties of the minimal orbit C of SO_n on its Lie algebra \mathfrak{o}_n . Unlike in the cases of \mathfrak{sl}_n and \mathfrak{sp}_{2n} , the sums kC are in general not closed, and only their closures are described explicitly here. The approach, though, is the same as for \mathfrak{sl}_n and \mathfrak{sp}_{2n} : we try to decrease the rank of a given element of \mathfrak{o}_n by subtracting an appropriate element of C. How this rank reduction works for \mathfrak{o}_n , and why it comes short of characterising the sets kC completely, is explained in Subsection 3.1. Subsections 3.2, 3.3, and 3.4 are devoted to determining $\overline{2C}$, $\overline{3C}$, and \overline{kC} for $k \geq 4$, respectively. In Subsection 3.2 we find that the complement of 2C in $\overline{2C}$ is a single nilpotent orbit, which discovery motivates the discussion of nilpotent orbits in Subsection 3.5.

3.1. The minimal orbit and rank reduction. We retain the notation ϕ and A^T from Section 2; only now they are defined with respect to the non-degenerate symmetric bilinear on $V = K^n$ defining the Lie algebra \mathfrak{o}_n . Recall that, for any $A \in \mathfrak{o}_n$ and $\lambda \in K$, the numbers λ and $-\lambda$ have the same (geometric and algebraic) multiplicity among the eigenvalues of A; moreover, $\operatorname{rk}(A)$ is even. The following lemma implies that every $A \in \mathfrak{o}_n$ of rank 2k is the sum of k rank two elements of \mathfrak{o}_n .

Lemma 3.1. Let $A \in \mathfrak{o}_n$, and let $J \in \mathfrak{gl}_n$ of rank one be such that $\mathrm{rk}(A-J) = \mathrm{rk}(A) - 1$. Then $\mathrm{rk}(A - (J - J^T)) = \mathrm{rk}(A) - 2$.

The proof of this lemma uses the useful identities $(y \otimes \eta)^T = \phi^{-1} \eta \otimes \phi y$ $(y \in V, \eta \in V^*)$ and $\phi A^T = A^* \phi$ $(A \in \mathfrak{gl}_n)$, whose proofs are straightforward.

Proof. By Lemma 2.1, there exist $x \in V$ and $\xi \in V^*$ such that $J = Ax \otimes A^*\xi$ and $\langle Ax, \xi \rangle = 1$; note that then $\ker(A - J) = \ker A \oplus Kx$. We have

$$J^T = \phi^{-1} A^* \xi \otimes \phi A x = A^T \phi^{-1} \xi \otimes (A^T)^* \phi x = A \phi^{-1} \xi \otimes A^* \phi x,$$

where the third step is justified by $A^T = -A$. In particular, we find that $\ker J^T$, too, contains $\ker A$, so that $\ker A \subseteq \ker(A - J + J^T)$. Moreover, we have

$$(A - J + J^{T})x = J^{T}x = \langle x, A^{*}\phi x \rangle A\phi^{-1}\xi = (Ax, x)A\phi^{-1}\xi = 0,$$

while $Ax \neq 0$. (In the last step we used $(Ax,x) = (x,A^Tx) = -(x,Ax) = -(Ax,x)$.) Hence, $\operatorname{rk}(A-J+J^T)$ is strictly smaller than $\operatorname{rk}(A)$; but as $A-J+J^T$ is skew symmetric, its ranks is even, hence equal to $\operatorname{rk}(A) = -(x,Ax) = -(x,Ax)$

If C would contain all elements of \mathfrak{o}_n of rank 2, then we would have $mC = \mathfrak{o}_n$ by this lemma. However, C is smaller; to characterise it we first describe the rank-two-elements of \mathfrak{o}_n .

Proposition 3.2. For any 2-dimensional subspace $W = \langle y_1, y_2 \rangle_K$ of V, the space $\{A \in \mathfrak{o}_n \mid \text{im } A \subseteq W\}$ is one-dimensional and spanned by $y_1 \otimes \phi(y_2) - y_2 \otimes \phi(y_1)$.

The proof of this proposition uses another easy observation; namely, that for any $A \in \mathfrak{o}_n$ the kernel of A is the orthogonal complement of A with respect to (.,.); we denote this orthogonal complement by $(\text{im } A)^{\perp}$.

Proof. Let $A \in \mathfrak{o}_n \setminus \{0\}$ have image contained in, and hence equal to, W; and let $x_1 \in V$ be such that $Ax_1 = y_1$. Then we have $(x_1, y_1) = (x_1, Ax_1) = 0$ by the skewness of A, so that $(x_1, y_2) = 0$ would imply $x_1 \in (\operatorname{im} A)^{\perp} = \ker A$, a contradiction, hence we may set $\alpha := 1/(x_1, y_2)$. Furthermore, $y_2^{\perp} \supseteq \ker A$, so that $J := \alpha y_1 \otimes \phi(y_2) \in \mathfrak{gl}_n$ satisfies the condition of Lemma 3.1. Then that lemma implies $A = \alpha(y_1 \otimes \phi(y_2) - y_2 \otimes \phi(y_1))$, as claimed.

Proposition 3.2 has the following interesting consequence.

Corollary 3.3. For each $k \in \{0,1,2\}$, the group SO_n acts transitively on the set $O_k := \mathbb{P}\{A \in \mathfrak{o}_n \mid \operatorname{rk}(A) = 2 \text{ and } (.,.)|_{\operatorname{im} A} \text{ has rank } k\} \subseteq \mathbb{P}\mathfrak{g}.$

Proof. It is not hard to see that SO_n acts transitively on the 2-dimensional subspaces of V on which (.,.) has rank k, and now the proposition can be applied. \square

The following corollary identifies $\mathbb{P}C$ with O_0 .

Corollary 3.4. The set C consists of all $A \in \mathfrak{o}_2$ with $\operatorname{rk}(A) \leq 2$ and $\operatorname{im} A$ isotropic with respect to (.,.). The latter condition is equivalent, for $A \in \mathfrak{o}_2$, to $A^2 = 0$.

Proof. By Corollary 3.3, it suffices to check that the highest root vector of \mathfrak{o}_n with respect to some choice of Borel and Cartan subalgebras has the stated properties, which is straightforward. As for the second statement: the radical of $(.,.)|_{\text{im }A}$ on im A is exactly ker $A \cap \text{im }A$, hence all of im A if and only if $A^2 = 0$.

We are now ready to state and prove our main rank reduction argument in the orthogonal case.

Proposition 3.5. Let $A \in \mathfrak{o}_n$ be of rank ≥ 4 . Then there exists a $J \in C$ such that $\operatorname{rk}(A - J) = \operatorname{rk}(A) - 2$.

Proof. On im A we have two bilinear forms: the restriction of (.,.), and a second form (.|.) defined by $(Ax_1|Ax_2) = (x_1, Ax_2)$; we continue to use \bot only for 'perpendicular with respect to (.,.)'. The second form is well-defined as $\ker A \bot \operatorname{im} A$ and skew-symmetric because

$$(Ax_2|Ax_1) = (x_2, Ax_1) = (A^Tx_2, x_1) = -(Ax_2, x_1) = -(x_1, Ax_2) = -(Ax_1|Ax_2).$$

Moreover, (.|.) is non-degenerate, as $(Ax_1|Ax_2)=0$ for all x_1 implies $x_1 \perp Ax_2$ for all x_1 , i.e., $Ax_2=0$. We may now apply Lemma 3.6 below to find a 2-dimensional subspace U of im A that is isotropic with respect to (.,.) but not with respect to (.|.). Choose a basis y_1, y_2 of U such that $(y_1|y_2)=1$, and set $J:=y_1\otimes\phi(y_2)-y_2\otimes\phi(y_1)$. Then im J is two-dimensional and isotropic with respect to (.,.), so J lies in C by Corollary 3.4. Furthermore, $\ker J = U^{\perp}$ contains $\ker A = (\operatorname{im} A)^{\perp}$, and if $x_1 \in A^{-1}y_1$, then

$$(A - J)x_1 = y_1 - (x_1, y_2)y_1 + (x_1, y_1)y_2 = y_1 - (y_1|y_2)y_1 + (y_1|y_1)y_2 = 0,$$

so that $\mathrm{rk}(A-J)$ is strictly smaller than $\mathrm{rk}(A)$; we conclude that J has the required properties. \Box

The proof above uses the following observation on bilinear forms.

Lemma 3.6. Let W be a K-vector space of finite dimension ≥ 4 equipped with a (possibly degenerate) symmetric bilinear form B_1 and a non-degenerate skew-symmetric bilinear form B_2 . Then there exists a 2-dimensional subspace of W that is isotropic with respect to B_1 but not with respect to B_2 .

The following proof, which is considerably shorter than our original proof, was suggested by Jochen Kuttler.

Proof. Suppose, on the contrary, that all 2-dimensional B_1 -isotropic subspaces of W are B_2 -isotropic, and note that then all B_1 -isotropic subspaces of any dimension are B_2 -isotropic. We may choose a basis e_1, \ldots, e_d of W such that $B_1(x,y) = \sum_{j=1}^l x_j y_j$, where $l \leq d$ is the rank of B_1 . If l = 0, 1, or 2, then the subspace of codimension 1 defined by the equation $x_1 = 0, x_1 = 0$, or $x_2 = ix_1$, respectively, is isotropic with respect to B_1 , and hence with respect to B_2 . On the other hand, any B_2 -isotropic subspace of W has dimension at most $\dim(W)/2$, so that $\dim(W)-1 \leq \dim(W)/2$, a contradiction to $\dim(W) \geq 4$.

Hence l is at least 3. Now consider the quadric $Q_1 := \{x \in W \mid B_1(x, x) = 0\}$. It is easy to find linearly independent vectors w_1, w_2, w_3 on Q_1 such that $B_1(w_j, w_k) \neq 0$ for all distinct $j, k \in \{1, 2, 3\}$ —for example, $w_1 = e_1 + ie_2, w_2 = e_1 + ie_3$, and

 $w_3 = e_2 + ie_3$. Moreover, Q_1 spans W and we may find $w_4, \ldots, w_d \in Q_1$ such that w_1, w_2, \ldots, w_d is a basis of W; we write w_j^{\perp} for $\{w \in W \mid B_1(w_j, w) = 0\}$. For each j and any $w \in Q_1 \cap w_j^{\perp}$ the space $Kw_j + Kw$ is B_1 -isotropic, so that $B_2(w_j, w) = 0$ by assumption. As, moreover, the restriction of B_1 to w_j^{\perp} has rank at least two, we find that $Q_1 \cap w_j^{\perp}$ spans w_j^{\perp} , so that $B_2(w_j, w) = 0$ for any $w \in w_j^{\perp}$. In other words, the linear function $B_2(w_j, .)$ is equal to $c_j B_1(w_j, .)$ for some $c_j \in K$, so that if A_1, A_2 are the matrices of B_1, B_2 with respect to w_1, \ldots, w_d , then

$$A_2 = \operatorname{diag}(c_1, \dots, c_d) A_1.$$

As A_2 is skew (with respect to transposition in the main diagonal) and A_1 is symmetric, we find that $c_j a_{jk} = -c_k a_{jk}$ for all j, k = 1, ..., d. By construction $a_{jk} \neq 0$ for distinct $j, k \in \{1, 2, 3\}$, and we find that $c_j = -c_k$ for all such j, k. This readily implies that $c_1 = c_2 = c_3 = 0$, so that A_2 is singular; but this contradicts the non-degeneracy of B_2 .

We can now prove Theorem 1.7; from the proof it will become clear why the rank reduction of Proposition 3.5 does not suffice to characterise the secant varieties of C completely.

Proof of Theorem 1.7. By Proposition 3.5 and induction, it suffices to prove that every element of \mathfrak{o}_n having rank 2 lies in 4C. By Corollary 3.3 (and the fact that 4C is, of course, a cone) it suffices to prove this for particular representatives of the projective orbits O_k (k=0,1,2) mentioned in that corollary. For k=0 we have $O_0 = \mathbb{P}C$, so there is nothing to prove. For k=1,2 let y_1,y_2,y_3,y_4 be linearly independent isotropic vectors in V satisfying $(y_1,y_3) = (y_2,y_4) = 1$ and $\langle y_1,y_3\rangle_K \perp \langle y_2,y_4\rangle_K$ (such vectors exist). Then a representative of O_1 is

$$(y_1 + y_3) \otimes \phi(y_2) - y_2 \otimes \phi(y_1 + y_3),$$

which can be written as

$$(y_1 \otimes \phi(y_2) - y_2 \otimes \phi(y_1)) + (y_3 \otimes \phi(y_2) - y_2 \otimes \phi(y_3)) \in 2C.$$

Similarly, a representative of O_2 is

$$(y_1 + y_3) \otimes \phi(y_2 + y_4) - (y_2 + y_4) \otimes \phi(y_1 + y_3),$$

which equals

$$(y_1 \otimes \phi(y_2) - y_2 \otimes \phi(y_1)) + (y_1 \otimes \phi(y_4) - y_4 \otimes \phi(y_1)) + (y_3 \otimes \phi(y_2) - y_2 \otimes \phi(y_3)) + (y_3 \otimes \phi(y_4) - y_4 \otimes \phi(y_3)) \in 4C.$$

One may think, now, that a representative of O_2 could already lie in kC for k=2 or 3—but this is not the case. Indeed, as we shall see in Subsection 3.3, such a representative does not even lie in $\overline{3C}$. This serves to show that the secant varieties of the minimal orbit in \mathfrak{o}_n are considerably more complicated than those of the minimal orbits in \mathfrak{sl}_n and \mathfrak{sp}_{2n} .

3.2. The first secant variety. The first secant variety $\mathbb{P}(\overline{2C}\setminus\{0\})$ of the minimal orbit in any simple Lie algebra is described in [14] as the union of a single (projective) semisimple orbit and several nilpotent orbits. We reprove this statement here for \mathfrak{o}_n ; first, because our method is different from that of Kaji et al and also applies to the second secant variety, and second, because we want to determine the complement $\overline{2C}\setminus 2C$ explicitly.

Before stating our characterisation of $\overline{2C}$, we recall that the closed subvariety

$$R_k := \{ A \in \mathfrak{o}_n \mid \operatorname{rk} A \le 2k \}$$

is irreducible for all k—this follows, for instance, from [11, Lemma 4.2.4(3)]—and we recall from the introduction the notation S_2 for the set of rank 4 semisimple elements having non-zero eigenvalues a, a, -a, -a.

Proposition 3.7. The affine variety

$$M := \{ A \in \mathfrak{o}_n \mid \operatorname{rk}(A) \leq 4 \text{ and } A^3 = \lambda A \text{ for some } \lambda \in K \}$$

has two irreducible components, namely R_1 and $\overline{2C}$. Furthermore, $\overline{2C}$ is equal to $\overline{S_2}$.

Recall, for the proof of this proposition, the notation $\mathcal{O}[\mathbf{d}]$ for the nilpotent O_n -orbit on \mathfrak{o}_n corresponding to the partition \mathbf{d} of n, where the even entries of \mathbf{d} are supposed to have even multiplicities. We work with O_n here, rather than with the adjoint group SO_n , not to have to distinguish between the two SO_n -orbits corresponding to *very even* partitions [7, 16]. Indeed, as both groups have the same minimal orbit $C = \mathcal{O}[2, 2, 1^{n-4}]$, this subtlety is immaterial to us.

We will not be able to avoid, in what follows, some explicit matrix computations. In these computations we always take for (.,.) the symmetric form given by $(x,y) = \sum_{i=1}^{n} x_i y_{n+1-i}$ with respect to the standard basis of $V = K^n$. The elements of \mathfrak{o}_n are then skew symmetric about the *skew* diagonal running from position (1,n) to position (n,1).

Proof of Proposition 3.7. For $J_1, J_2 \in C$ we have

$$(J_1 + J_2)^3 = J_1 J_2 J_1 + J_2 J_1 J_2,$$

where we use that $J_i^2=0$ for i=1,2 (Corollary 3.4). The map $J_1J_2J_1$ is skew-symmetric and its image is contained in im J_1 , hence by Proposition 3.2 $J_1J_2J_1=c_1J_1$ for some $c_1\in K$. Similarly, $J_2J_1J_2=c_2J_2$ for some $c_2\in K$. If $J_1J_2=0$, then $c_1=c_2=0$ and $J_1+J_2\in M$ (with $\lambda=0$). Otherwise, let $x\in V$ be such that $J_1J_2x\neq 0$. Then

$$c_2J_1J_2x = J_1(J_2J_1J_2)x = (J_1J_2J_1)J_2x = c_1J_1J_2x$$

so that $c_1 = c_2$. This shows that $J_1 + J_2$ lies in M (with $\lambda = c_1$), so that $\overline{2C} \subseteq M$. The inclusion $R_1 \subseteq M$ is immediate: an element A of R_1 is either semisimple with non-zero eigenvalues a, -a, so that $A \in M$ (with $\lambda = a^2$), or it is nilpotent of nilpotence degree at most 3, and then A also lies in M (with $\lambda = 0$).

Conversely, let A be in M and let $\lambda \in K$ be such that $A^3 = \lambda A$. If $\lambda = 0$, then $A^3 = 0$, which together with the condition that $\operatorname{rk}(A)$ be at most 4 shows that A lies in a nilpotent orbit corresponding to one of the partitions $[3,3,1^{n-6}]$, $[3,2,2,1^{n-7}]$, $[3,1^{n-3}]$, $[2,2,2,2,1^{n-8}]$, $[2,2,1^{n-4}]$, or $[1^n]$. The first among these is greater than all of the other five in the usual order on partitions [7], so that the corresponding orbit closure contains the other five nilpotent orbits.

Suppose, on the other hand, that $\lambda \neq 0$, and let a be a square root of λ . Then A is a zero of the square-free polynomial t(t-a)(t+a), hence semisimple. There are three possibilities: either A=0, or $A \in R_1$ with non-zero eigenvalues $\pm a$, or $A \in S_2$ with eigenvalues a, a, -a, -a. Together with the above discussion of the nilpotent orbits in M this implies $M = R_1 \cup S_2 \cup \overline{\mathcal{O}}[3, 3, 1^{n-6}]$. We shall show that the last two terms are contained in $\overline{2C}$, so that

$$M = R_1 \cup \overline{2C}$$
:

as R_1 and $\overline{2C}$ are both irreducible and neither of these sets is contained in the other, this implies the first statement of the proposition. Moreover, the above shows that the complement of S_2 in $\overline{2C}$ equals $(R_1 \cap \overline{2C}) \cup \overline{\mathcal{O}}[3,3,1^{n-6}]$, so that S_2 is open, and hence dense, in $\overline{2C}$ —which proves the second statement of the proposition.

Suppose, therefore, that A lies in $\mathcal{O}[3,3,1^{n-6}]$. Then A is conjugate to an $n \times n$ -matrix that has a 6×6 block

in the middle, and zeroes elsewhere (off-diagonal zeroes are omitted). Now both matrices on the right-hand side of the equality lie in C: they have rank 2 and isotropic images. Therefore, A lies in 2C and $\overline{\mathcal{O}}[3,3,1^{n-6}] \subseteq 2C$.

Next assume that A has rank 4 and is semisimple with non-zero eigenvalues a, a, -a, -a. Then A is conjugate to a matrix with a 4×4 -block

$$a \begin{bmatrix} 1 & & & & \\ & 1 & & & \\ & & -1 & \\ & & & -1 \end{bmatrix} = \frac{a}{2} \begin{bmatrix} 1 & & 1 & & \\ & 1 & & -1 \\ -1 & & -1 & \\ & 1 & & -1 \end{bmatrix} + \frac{a}{2} \begin{bmatrix} 1 & & -1 & & \\ & 1 & & 1 \\ 1 & & -1 & \\ & -1 & & -1 \end{bmatrix}$$

in the middle and zeroes elsewhere. One readily verifies that the two terms on the left-hand side lie in C, so that $A \in 2C$. As explained above, this concludes the proof of the proposition.

Now that we have identified $\overline{2C}$ as the irreducible component $\overline{S_2}$ of M—and hence proved the first part of Theorem 1.3—we investigate the set 2C itself. It is easy to verify, like we did in the proof above for $\mathcal{O}[3,3,1^{n-6}]$, that the nilpotent orbits $\mathcal{O}[3,1^{n-3}]$, $\mathcal{O}[2,2,2,2,1^{n-8}]$, $\mathcal{O}[2,2,1^{n-4}]$, and $\mathcal{O}[1^n]$ in $\overline{S_2}$ all lie in 2C (in fact, this follows from the computations in Subsection 3.5 below), as does S_2 by the explicit computation in the proof above. Thus we find that $\overline{2C} \setminus 2C$ is contained in $\mathcal{O}[3,2,2,1^{n-7}]$. Note that an element A from this nilpotent orbit has $\mathrm{rk}(A)=4$ and $\mathrm{rk}(A^2)=1$. The following lemma shows that an element of 2C cannot have this property, thus proving Proposition 1.5.

Lemma 3.8. If $A \in 2C$ has rank 4, then $rk(A^2)$ is even.

Proof. By Corollary 3.4 we may write

$$A = y_1 \otimes \phi(y_2) - y_2 \otimes \phi(y_1) + y_3 \otimes \phi(y_4) - y_4 \otimes \phi(y_4),$$

where $\langle y_1, y_2 \rangle_K$ and $\langle y_3, y_4 \rangle_K$ are isotropic. By the condition that $\operatorname{rk}(A)$ be 4, the vectors y_1, y_2, y_3, y_4 are a basis of im A. The matrix of $(.,.)|_{\operatorname{im} A}$ with respect to this

basis is of the form

$$\begin{bmatrix} 0 & M \\ M^t & 0 \end{bmatrix},$$

where M^t is the (ordinary) transpose of the 2×2 -matrix M. We conclude that $\operatorname{rk} A^2 = \operatorname{rk}(.,.)|_{\operatorname{im} A} = 2\operatorname{rk} M$.

3.3. The second secant variety. To characterise $\overline{3C}$ we proceed as in the first part of the proof of Proposition 3.7: we take three arbitrary elements J_1, J_2, J_3 of C, and use the relations provided by Proposition 3.2 to find a polynomial annihilating $J_1 + J_2 + J_3$. Conversely, we show that semisimple elements having a characteristic polynomial of that form do indeed lie in 3C.

Proposition 3.9. Any element of $\overline{3C}$ is annihilated by a polynomial of the form

$$t(t-a)(t-b)(t-c)(t+a)(t+b)(t+c)$$

for some $a, b, c \in K$ with a + b + c = 0.

Proof. The set of matrices in \mathfrak{o}_n that are annihilated by such a polynomial, is closed, so that it suffices to prove the proposition for elements of 3C. Let therefore J_1, J_2, J_3 be elements of C. From the proof of Proposition 3.7 we know that there exist constants $c_{ik} = c_{ki}$ such that

$$J_i J_k J_i = c_{ik} J_i$$
 for all $i, k \in \{1, 2, 3\}, i \neq k$.

Similarly, there exists a $c \in K$ with

$$J_1(J_2J_3J_1J_2J_3 + J_3J_2J_1J_3J_2)J_1 = cJ_1;$$

indeed, the matrix between brackets is an element of \mathfrak{o}_n , so that the matrix on the left-hand side lies in \mathfrak{o}_n . Furthermore, its image is contained in im J_1 , whence the existence of such a c follows from Proposition 3.2. In fact, one can show that the same c satisfies the above relation with 1, 2, 3 permuted cyclically. Using these relations, a straightforward calculation shows that

$$tp(t)$$
 with $p(t) := (t^3 - (c_{12} + c_{13} + c_{23})t)^2 - c - 2c_{12}c_{13}c_{23}$

annihilates $J_1 + J_2 + J_3$. Now we need only check that p has the desired form. To this end, let μ be a square root of $c + 2c_{12}c_{13}c_{23}$, so that p factorises into

$$p(t) = (t^3 - (c_{12} + c_{13} + c_{23})t + \mu)(t^3 - (c_{12} + c_{13} + c_{23})t - \mu).$$

The first of these factors lacks a term with monomial t^2 ; hence, the sum of its zeroes a, b, c is 0. The second factor has zeroes -a, -b, -c, and this concludes the proof of the proposition.

Remark 3.10. The polynomial tp(t) appearing in the proof above was found as follows: consider the free associative algebra F (with one) over the ground field $K(c_{12}, c_{13}, c_{23}, c)$ with generators J_1, J_2, J_3 and let I be the ideal generated by the relations appearing in the proof above. Then a (non-commutative) Gröbner basis computation of I shows that F/I has dimension 37, and the polynomial tp(t) is the minimal polynomial of $J_1 + J_2 + J_3$ in this quotient. For this computation we used the GAP-package GBNP written by Cohen and Gijsbers [5, 9] (with concrete values for the c_{ij} and c), together with some $ad\ hoc$ programming of our own in Mathematica.

A partial converse to the proposition above is the following lemma, in whose proof we compute with respect to the fixed bilinear form of Subsection 3.2.

Lemma 3.11. For all $a, b \in K$, any semisimple element of so_n whose eigenvalues (with multiplicities) are 0 (n-6 times) and a, b, -a-b, -a, -b, a+b for some $a, b \in K$, lies in 3C.

Proof. Let A be such an element; we may suppose that A is non-zero. Then the numbers a,b,-a-b are not all equal, and by permuting them we may assume that $a \neq b$. Now A is conjugate to an $n \times n$ -matrix having zeroes everywhere except for a 6×6 -block in the middle, which is of the form

The first term on the right-hand side lies in C, as it has rank 2 and its image is isotropic. We claim that the second term on the right-hand side, which we denote by B, lies in 2C. To see this, note that $(b, -a, 0, 0, 0, 0)^t$, $(0, 0, 1, 0, 0, 0)^t$, and $(a, -b, 0, 0, 0, 0)^t$ are eigenvectors of B with eigenvalues 0, a + b, and a + b, respectively. It follows that B has rank 4 and that -a - b, as well, has multiplicity two among the eigenvalues of B; hence B lies in C by Propositions 1.5 and 3.7, and C lies in C.

To finish our characterisation of $\overline{3C}$, recall that R_k is the set of all elements of \mathfrak{o}_n having rank $\leq 2k$. We now need an argument why S_3 , the set of all semisimple elements in R_3 having 6 distinct eigenvalues a, b, c, -a, -b, -c such that a+b+c=0, is dense in $\overline{3C}$. The following lemma will provide such an argument.

Lemma 3.12. For any k, the subset T_k of R_k consisting of all elements having 2k distinct non-zero eigenvalues, is open in R_k .

Proof. An element of R_k lies in $R_k \setminus T_k$ if and only if it has a characteristic polynomial of the form

$$t^{n-2k}(t^2-a_1)^2(t^2-a_2)(t^2-a_3)\dots(t^2-a_{k-1})$$

for some $a_1, \ldots, a_{k-1} \in K$. The map $K^{k-1} \to K^{n+1}$ sending (a_1, \ldots, a_{k-1}) to the coefficients of the monomials t^i in the polynomial above has a closed image Y, and $R_k \setminus T_k$ is the inverse image of Y under the polynomial map sending a matrix to the coefficients of its characteristic polynomial.

From Proposition 3.9 and Lemma 3.11 we have

$$S_3 = T_3 \cap \overline{3C}$$
.

By the lemma above, this set is open, and hence dense, in $\overline{3C}$, so that $\overline{3C} = \overline{S_3}$ as claimed in Theorem 1.3.

Proposition 3.13. The set 4C contains a dense subset of R_4 .

Together with the obvious inclusion $4C \subseteq R_4$, this proposition implies $\overline{4C} = R_4$. Using Proposition 3.5 we then find $\overline{kC} = R_{2k}$ for all $k \ge 4$, as claimed in Theorem 1.3.

Proof. Let a_1, a_2, a_3, a_4 be variables. It suffices to prove that the diagonal matrix

$$A = diag\{a_1, \dots, a_4, -a_4, \dots, -a_1\}$$

lies in $4C(K(a_1,\ldots,a_4))$, i.e., 4 times the minimal orbit in \mathfrak{o}_8 with coordinates in $K(a_1,\ldots,a_4)$. Indeed, if this is the case, then a generic semisimple element of R_4 lies in 4C, and these elements are dense in R_4 by Lemma 3.12. Define the expressions

$$r_1 := 0, s_1 := 1,$$

$$r_2 := a_3(a_1^2 - (a_2 + a_3 + a_4)^2), s_2 := 4(a_2 + a_3)(a_3 + a_4),$$

$$r_3 := -a_4(a_1^2 - (-a_2 + a_3 + a_4)^2), s_3 := 4(a_3 + a_4)(-a_2 + a_4),$$

$$r_4 := -a_2(a_1^2 - (-a_2 - a_3 + a_4)^2), \text{ and } s_4 := 4(-a_2 + a_4)(-a_2 - a_3);$$

and note that the transformation $a_2 \mapsto a_3 \mapsto a_4 \mapsto -a_2$ cyclically permutes s_2, s_3, s_4 , and does the same with r_2, r_3, r_4 up to a change of sign. Now set

$$y_1 := (0, r_4, 0, r_3, 0, r_2, 0, r_1)^t,$$
 $y_2 := (\frac{1}{s_1}, 0, \frac{1}{s_2}, 0, \frac{1}{s_3}, 0, \frac{1}{s_4}, 0)^t,$ and $J := y_1(y_2^t F) - y_2(y_1^t F),$

where $F=(\delta_{i+j,9})_{ij}$ is the 8×8 -matrix representing the form (.,.). By construction J lies in $\mathfrak{o}_n(K(a_1,\ldots,a_4))$ and has rank 2. It is easy to see that $y_1^tFy_1=y_2^tFy_2=0$, and a straightforward computation shows that $y_1^tFy_2=\sum_{i=1}^4\frac{r_i}{s_i}$ is zero, as well. This shows that im J is isotropic, hence J lies in $C(K(a_1,\ldots,a_4))$. A direct computation (preferably by a computer algebra system; we used Mathematica) shows that A-J is semisimple with eigenvalues

$$0, 0, \mp a_1, \pm \frac{1}{2}(a_1 - a_2 + a_3 - a_4), \pm \frac{1}{2}(a_1 + a_2 - a_3 + a_4);$$

if we take the upper one of the two signs in each of the last three eigenvalues, then they add up to zero, so that $A - J \in 3C(K(a_1, \ldots, a_4))$ by Lemma 3.11. We conclude that A lies in $4C(K(a_1, \ldots, a_4))$ as claimed.

Remark 3.14. By studying the computations needed for the proof above, it should be straightforward to prove that *any* semisimple element of R_4 lies in 4C. Furthermore, the computation proving Lemma 3.11 is easily modified to a proof that for any semisimple $A \in \mathfrak{o}_n$ of rank 2k, $k \geq 2$, there exists an element $J \in C$ such that $\operatorname{rk}(A-J) = \operatorname{rk}(A) - 2$ and A-J is again semisimple (this is a 'semisimple version' of Proposition 3.5). Summarising, this would prove that for $k \geq 4$ any semisimple element of R_k lies in kC.

3.5. Nilpotent orbits. As we have seen in Subsection 3.2, the set $\overline{2C} \setminus 2C$ consists of the single nilpotent orbit $\mathcal{O}[3,2,2,1^{n-7}]$. This motivates the question of what the minimal k is such that a given nilpotent orbit \mathcal{O} lies in kC. We will see that usually, this k is just half the rank of \mathcal{O} . However, this is not true for the orbits $\mathcal{O}[3,1^{n-3}]$, $\mathcal{O}[3,2,2,1^{n-3}]$, and $\mathcal{O}[5,1^{n-5}]$. Furthermore, it remains an open question what the minimal k is for partitions whose odd entries are all smaller than 6. The following lemma will be used to handle odd entries of size greater than 6.

Lemma 3.15. The nilpotent orbit $\mathcal{O}[7] \subseteq \mathfrak{o}_7$ is contained in 3C.

In the calculation proving this lemma, as in the rest of this subsection, we compute with concrete matrices that are skew-symmetric with respect to the bilinear form $(x,y) := \sum_i x_i y_{n+1-i}$.

Proof. A straightforward computation shows that the difference

is semisimple with three double eigenvalues $0, \frac{i}{2}$, and $-\frac{i}{2}$, so that it lies in 2C by the proof of Proposition 3.7. As the matrix on the right lies in $\mathcal{O}[7]$ and the matrix of the left lies in C, this proves the lemma.

Recall from the introduction the notation $l(\mathbf{d})$ for the number of odd entries of \mathbf{d} that are greater than 1. We are now in a position to prove Theorem 1.6.

Proof of Theorem 1.6. We prove the statement for partitions [r, r] (with r > 1), [2r + 1, 2s + 1] (with r > s > 0) and [2r + 1] (with r > 2). The result will then follow by pairing equal even entries, pairing odd entries > 1, taking $[d_1]$ if l is odd, and forming appropriate block matrices.

The orbit $\mathcal{O}[r, r]$ is represented by a $2r \times 2r$ -matrix of the following form (drawn here for r = 3):

$$\begin{bmatrix}
0 & 1 & & & & & \\
& 0 & 1 & & & & \\
& & 0 & & & & \\
& & & & 0 & -1 & \\
& & & & 0 & -1 & \\
& & & & & 0
\end{bmatrix}.$$

This matrix is equal to $(E_{1,2} - E_{2r-1,2r}) + \cdots + (E_{r-1,r} - E_{r+1,r+2})$ (where E_{ij} is the matrix with an entry 1 at (i,j) and zeroes elsewhere). These r-1 matrices all belong to C (cf. Corollary 3.4), hence $\mathcal{O}[r,r] \in (r-1)C$.

Next we consider the orbit $\mathcal{O}[2r+1,2s+1]$ with r>s>0. There is a simple recipe for finding a representative of this orbit [7, Recipe 5.2.4]; by way of example, the orbit $\mathcal{O}[7,3]$ is represented by (leaving out the off-diagonal zeroes):

$$\begin{bmatrix} 0 & 1 & & & & & & & & \\ & 0 & 1 & 1 & & & & & & \\ & 0 & 1 & 1 & & & & & \\ & & 0 & 1 & 1 & & & & \\ & & & 0 & -1 & & & \\ & & & & 0 & -1 & -1 & & \\ & & & & 0 & -1 & & \\ & & & & 0 & -1 & & \\ & & & & 0 & -1 & & \\ & & & & 0 & 0 & -1 & \\ & & & & & 0 & 0 & -1 & \\ & & & & & 0 & 0 & -1 & \\ & & & & & 0 & 0 & -1 & \\ & & & & & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & 0 & -1 & \\ & & & & & 0 & 0 & 0 & 0 & -1 & \\ & & & & 0 & 0 & 0 & 0 & 0 & -1 & \\ & & & & 0 & 0 & 0 & 0 & 0 & -1 & \\ & & & & 0 & 0 & 0 & 0 & 0 & -1 & \\ & & & 0 & 0 & 0 & 0 & 0 & -1 & \\ & & & 0 & 0 & 0 & 0 & 0 & -1 & \\ & & & 0 & 0 & 0 & 0 & 0 & -1 & \\ & & & 0 & 0 & 0 & 0 & 0 & -1 & \\ & & 0 & 0 & 0 & 0 & 0 & 0 & -1 & \\ & & 0 & 0 & 0 & 0 & 0 & 0 & -1 & \\ & & 0 & 0 & 0 & 0 & 0 & 0 & -1 & \\ & & 0 & 0 & 0 & 0 & 0 & 0 & -1 & \\ & 0$$

This matrix lies in 4C, as it is the sum of $E_{1,2} - E_{9,10}$, $E_{2,3;4} - E_{7;8,9}$, $E_{3;4,5} - E_{6,7;8}$, and $E_{4,6} - E_{5,7}$, where we use the shorthand notation $E_{i,j_1;j_2}$ for $E_{i,j_1} + E_{i,j_2}$, and its analogue for rows. These matrices all belong to C by Corollary 3.4, and a moment's reflection shows that this, too, generalises to the case where r and s are arbitrary, proving that $\mathcal{O}[2r+1,2s+1] \subseteq (r+s)C$.

Finally, the orbit $\mathcal{O}[2r+1]$ with r>2 has a representative of the form drawn in Lemma 3.15 for r=3. Subtracting the (r-3) matrices $E_{1,2}-E_{2r,2r+1},E_{2,3}-E_{2r-1,2r},\ldots,E_{r-3,r-2}-E_{r+4,r+5}\in C$ yields a matrix with zeroes everywhere except for the 7×7 -block of Lemma 3.15 in the middle; that lemma shows that this matrix lies in 3C. Hence, $\mathcal{O}[2r+1]\subseteq rC$.

To conclude the proof, consider first the case where $l(\mathbf{d})$ is even. We then partition the entries of \mathbf{d} that are greater than 1 into pairs of the forms [r, r] and [2r+1, 2s+1] as above. In the case where $l(\mathbf{d})$ is odd and $d_1 > 5$, we decompose the entries d_2, \ldots, d_m as in the first case, and form the singleton $[d_1]$. In both cases, a representative of $\mathcal{O}[\mathbf{d}]$ is then found by gluing the block matrices corresponding to the pairs, and in the second case the block matrix corresponding to the singleton $[d_1]$, together in an appropriate way. The above calculations show that $\mathcal{O}[\mathbf{d}]$ lies in $(\operatorname{rk}(A)/2)C$, as claimed.

We conclude by recalling that, for some nilpotent orbits \mathcal{O} , half the rank of \mathcal{O} does *not* suffice!

Lemma 3.16. We have $\mathcal{O}[3,1^{n-3}] \subseteq 2C \setminus C$ and $\mathcal{O}[3,2,2,1^{n-7}], \mathcal{O}[5,1^{n-5}] \subseteq 3C \setminus 2C$.

Proof. The first statement follows from Corollary 3.4: the matrix corresponding to the partition $[3, 1^{n-3}]$ has a non-zero square. It is clear that the orbits in the second statement are contained in 3C. The claim follows then with Lemma 3.8, since both orbits have rank 4 and the square of a representative has rank 1 for the first, and 3 for the second orbit.

The nilpotent orbits of smallest rank for which we do not know the smallest k such that kC contains them, are therefore $\mathcal{O}[3,3,3,1^{n-9}]$ and $\mathcal{O}[5,2,2,1^{n-9}]$, which are both of rank 6.

4. Conclusion and further research

We have successfully determined, for all classical simple Lie algebras \mathfrak{g} and all $k \geq 1$, the sets \overline{kC} where C is the adjoint orbit of long root vectors, or, in the

terminology of [6], of extremal elements. If \mathfrak{g} is \mathfrak{sl}_n or \mathfrak{sp}_{2n} , then the sets kC are closed, and the minimal k for which they fill the whole space \mathfrak{g} is equal to n or 2n, respectively. If, on the other hand, \mathfrak{g} is \mathfrak{o}_n , then 2C is not closed, and we only know that the minimal k for which kC is equal to \mathfrak{o}_n lies between $\lfloor \frac{n}{2} \rfloor$ and $\lfloor \frac{n}{2} \rfloor + 3$.

We conclude our paper with two rather speculative directions of further research, suggested by our findings. First, it is shown in [6] that the minimal number of elements of C needed to generate \mathfrak{g} as a Lie algebra, is equal to n for \mathfrak{sl}_n , equal to 2n for \mathfrak{sp}_{2n} , and equal to $\lceil \frac{n}{2} \rceil$ for \mathfrak{o}_n . Of course, the similarity with the numbers that we listed above may be a coincidence, but if there should be a direct argument that these numbers are indeed equal, then the results of [6] could be used in solving the remaining open question concerning \mathfrak{o}_n , and in determining the secant varieties of the minimal orbit in the exceptional Lie algebras, as well.

As mentioned in the introduction, this paper is part of a rather ambitious project, namely: determining the higher secant varieties of the minimal orbit in arbitrary irreducible representations of reductive groups. In that setting, too, the complement of kC in \overline{kC} is worth investigation. The insight that, in the case of \mathfrak{o}_n , the complement of 2C in $\overline{2C}$ consists of a nilpotent orbit, suggests, in the general setting, that $\overline{kC} \setminus kC$ may be always contained in the null cone. However, if this were true, then it would follow from our Theorem 1.6 that $\lfloor \frac{n}{2} \rfloor C$ is already all of \mathfrak{o}_n , contrary to what a guess along the lines of the previous paragraph would yield.

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